

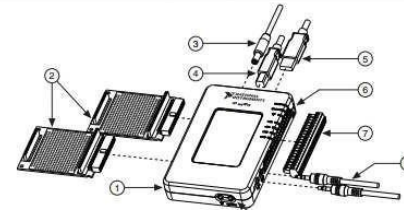
# SFWR ENG 4AA4 Lab 6



## NI myRIO-1900

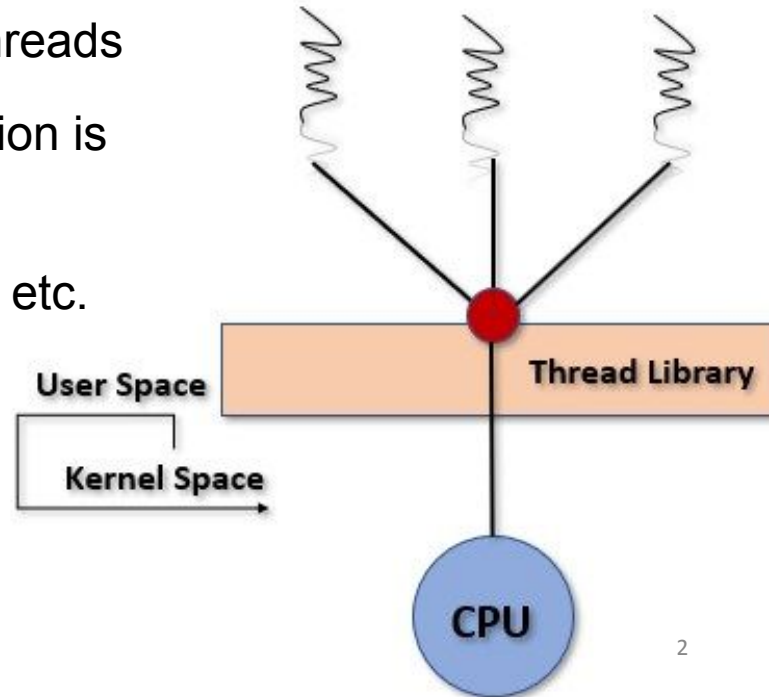
The National Instruments myRIO-1900 is a portable reconfigurable I/O (RIO) device that students can use to design control, robotics, and mechatronics systems. This document contains pinouts, connectivity information, dimensions, mounting instructions, and specifications for the NI myRIO-1900.

Figure 1. NI myRIO-1900



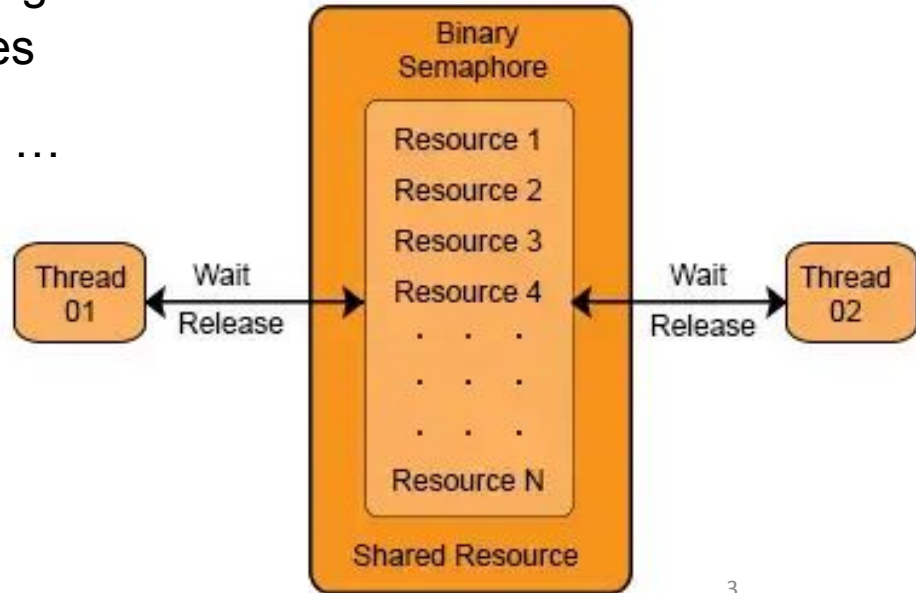
# Lab 6 Introduction

- ❖ Create aperiodic task as threads
- ❖ Observe why synchronization is needed
- ❖ Race condition, starvation, etc.



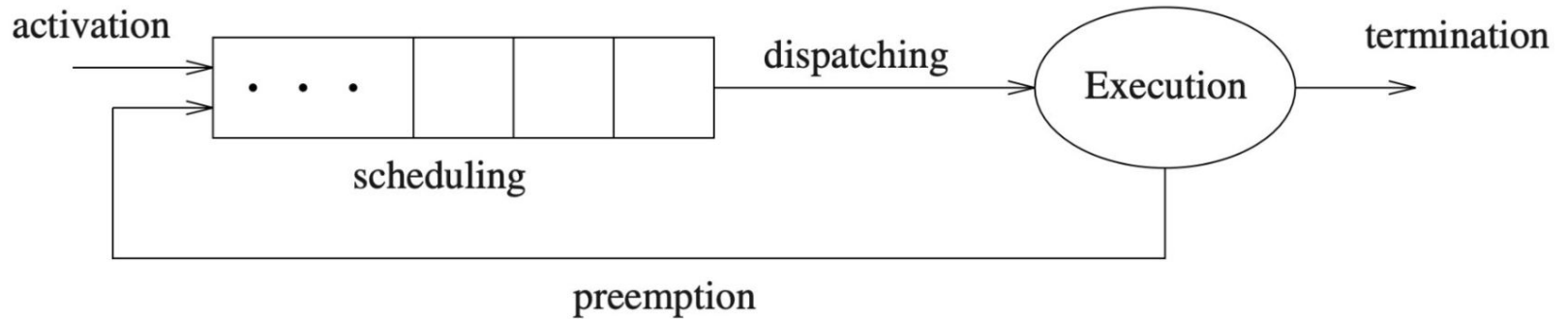
# Lab 6 Introduction

- ❖ Synchronize threads using semaphores and mutexes
- ❖ POSIX pthreads, sem\_t, ...



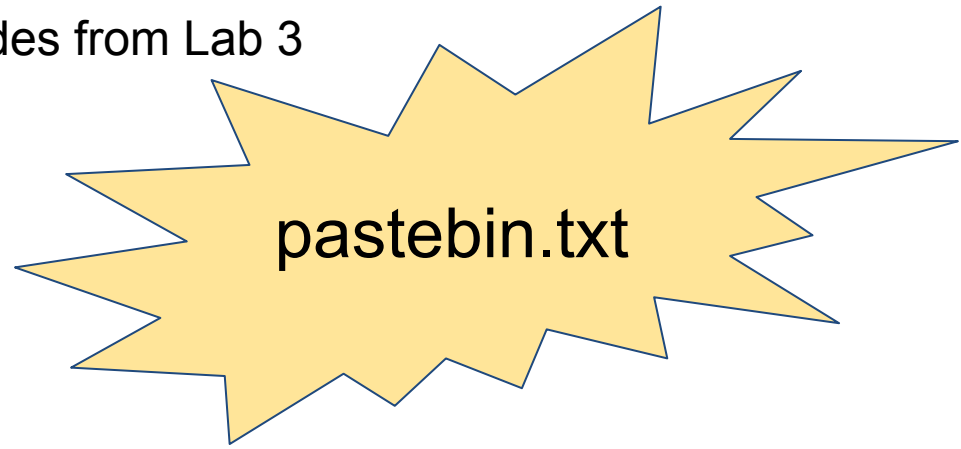
# Lab 6 Introduction

- ❖ Experiment with different scheduling policies

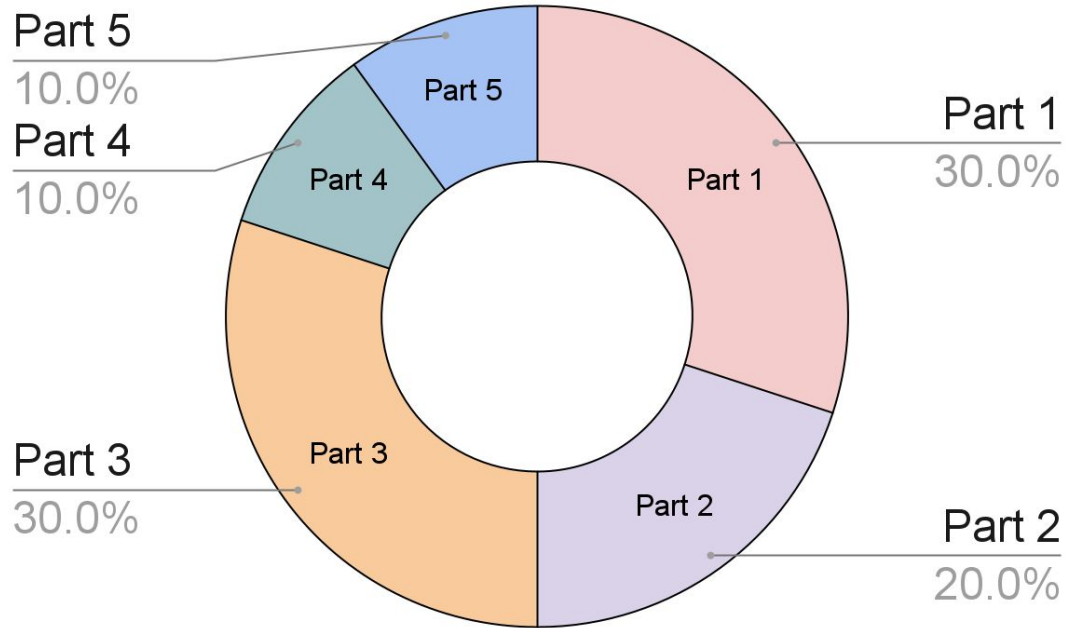


# Reminders

- ❖ Part 1 in Lab 3, “Hello world” C project
- ❖ No need for myRIO templates
- ❖ Compiler, linker flags, includes from Lab 3



# Marking Scheme



# One more thing...

- ❖ Part 5: Google Doc
- ❖ Experiments in Linux VM: execute in sudo

GL HF :)