

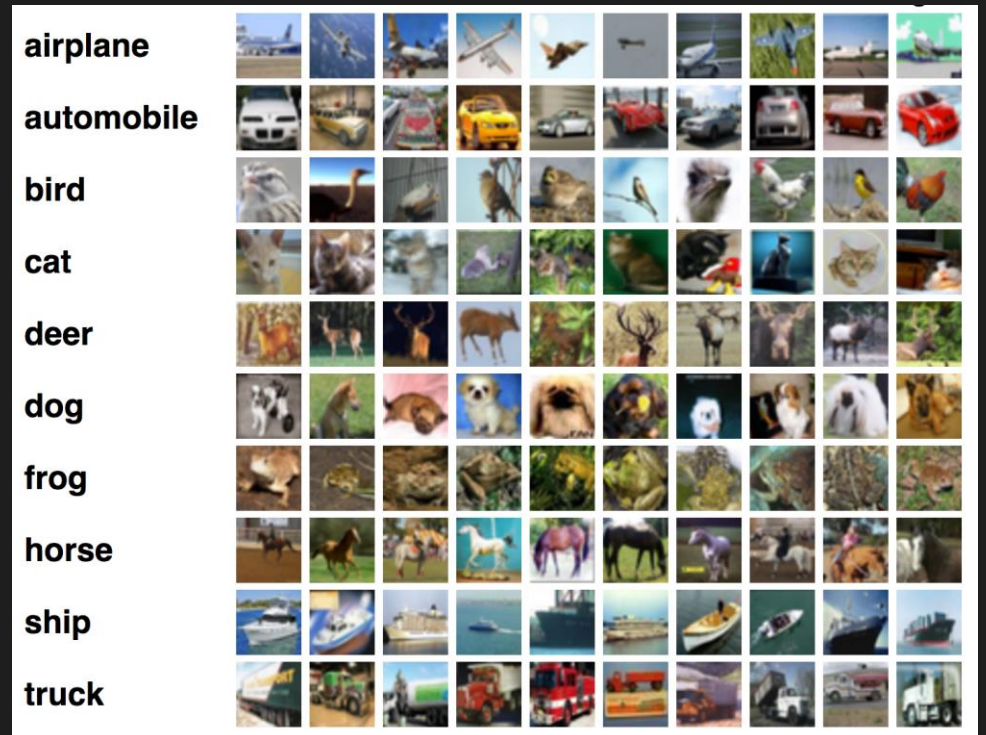
INTRODUCTION TO MACHINE LEARNING COMPSCI 4ML3

LECTURE 13

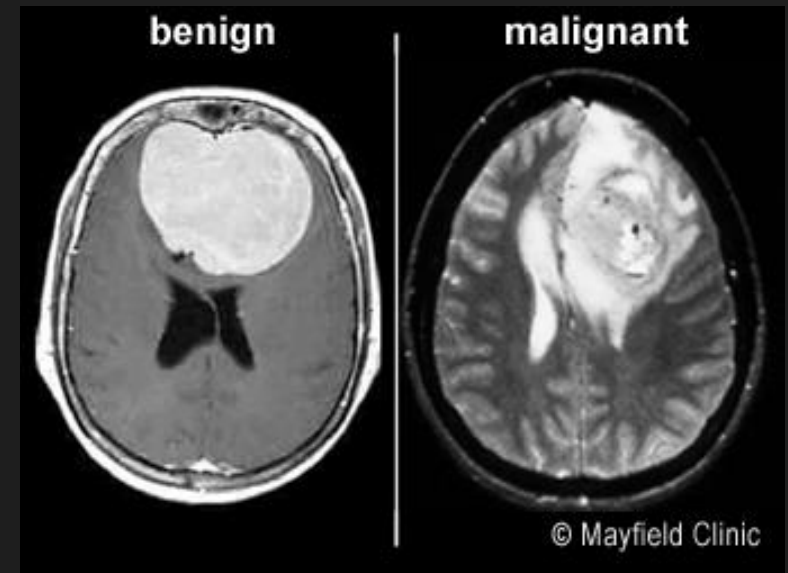
HASSAN ASHTIANI

CLASSIFICATION

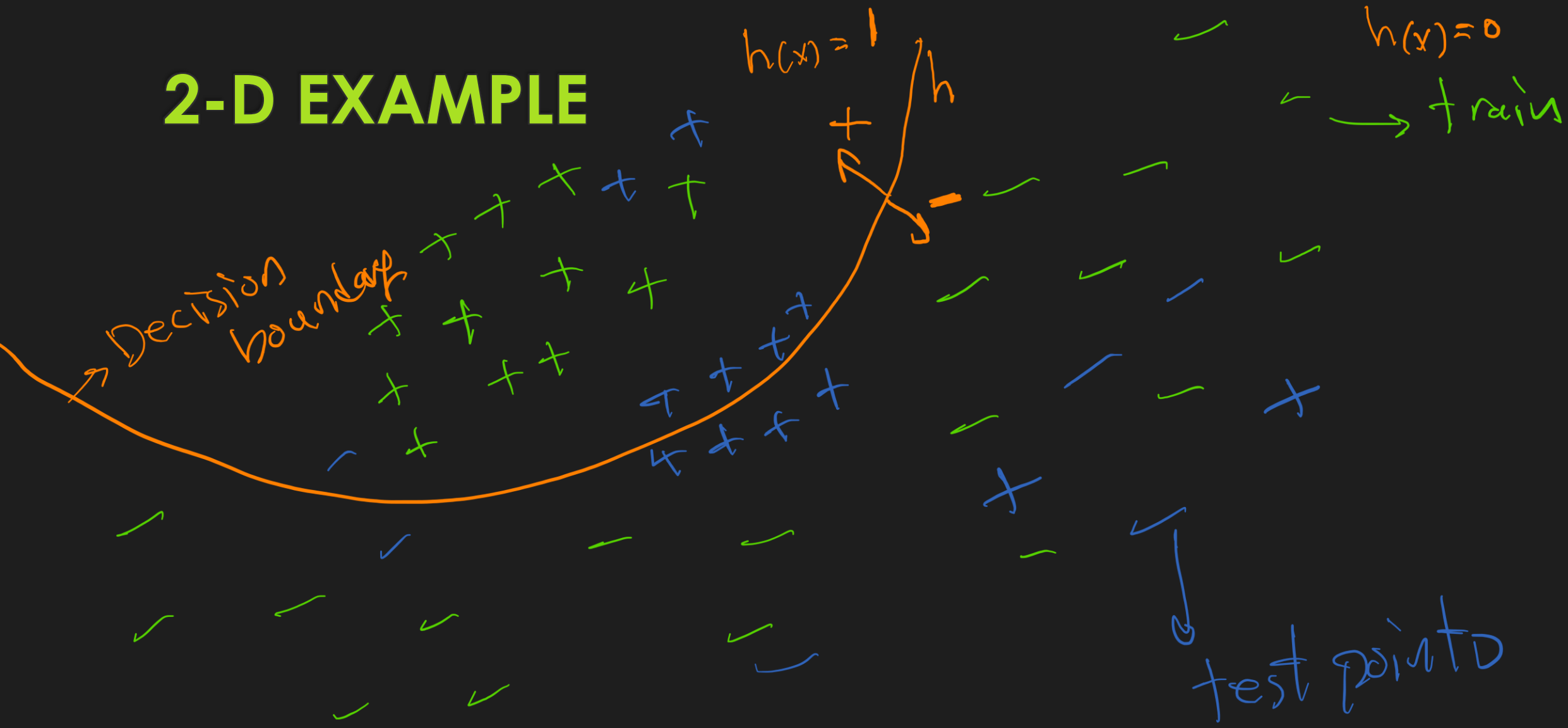
- PREDICT THE CATEGORY
- *k*-CLASS CLASSIFICATION
 - $y \in \{1, 2, 3, \dots, k\}$



1	2	5	9	7	6	3	5	0	8
4	5	8	6	9	3	2	9	7	2
3	3	3	9	5	0	3	2	3	0
1	1	4	0	2	1	5	3	3	6
8	6	2	0	4	0	4	5	3	9
9	5	4	2	2	7	1	6	0	9
1	7	0	3	9	1	7	0	7	7
2	6	5	1	6	4	2	2	2	9
4	4	4	2	0	6	9	4	8	3
1	5	0	3	4	6	8	2	5	1



2-D EXAMPLE



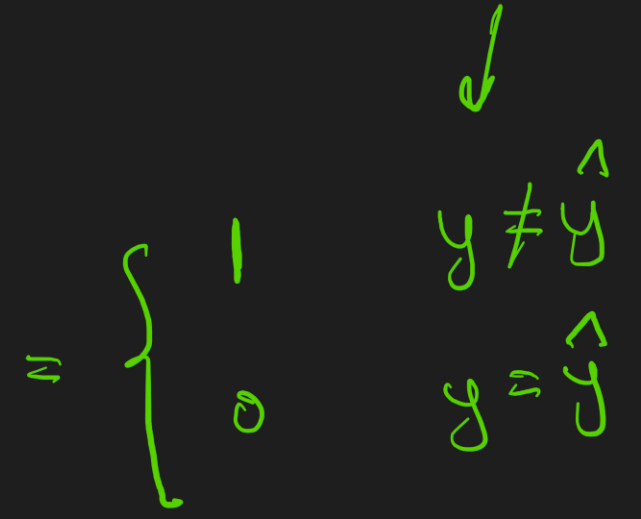
ACCURACY, 0-1 LOSS

- FOR REGRESSION WE USED THE SQUARED LOSS

- $l(y, \hat{y}) = (y - \hat{y})^2$.

- LOSS FOR CLASSIFICATION?

- THE ZERO-ONE LOSS (ERROR): $l^{0-1}(y, \hat{y}) = 1_{y \neq \hat{y}}$



- PREDICTOR/LABELING-FUNCTION: $h: X \rightarrow Y$

- TRAINING SET: $Z = ((x^1, y^1), \dots, (x^m, y^m))$

- GENERATED FROM D_{XY} , OR D FOR SHORT

- EMPIRICAL (TRAINING) ERROR OF h : $L_Z^{0-1}(h) = \frac{1}{m} \sum_i l^{0-1}(h(x^i), y^i)$

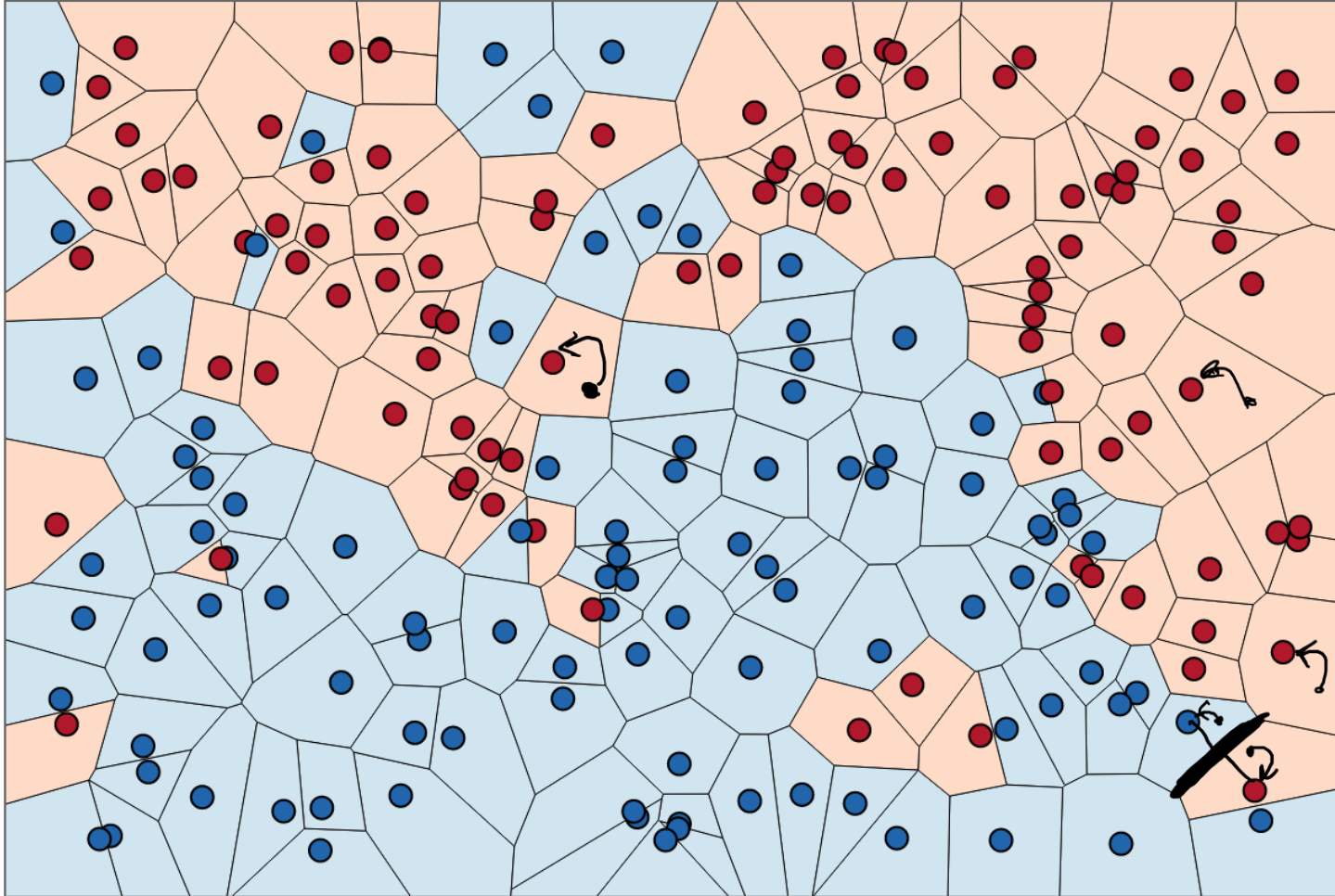
- EXPECTED ERROR OF h : $L_D^{0-1}(h) = \mathbb{E}_{(x,y) \sim D} l^{0-1}(h(x), y)$

THE NEAREST NEIGHBOR CLASSIFIER

- $\hat{y}(x; Z) =$
 - FIND THE CLOSEST x' TO x IN THE DATA SET
 - $\min_{x'} \|x - x'\|_2$
 - OUTPUT THE LABEL OF x'
- DECISION BOUNDARY?

VORONOI DIAGRAM

↑
↓
+
-
+
-
+
-



NEAREST NEIGHBOR: PROS AND CONS

- PROS

- BASICALLY NO TRAINING IS NEEDED. ✓

- NO PARAMETER OR HYPER-PARAMETER ✓

- EASY TO IMPLEMENT ✓

- POWERFUL AND FLEXIBLE ✓

- NON-PARAMETRIC!

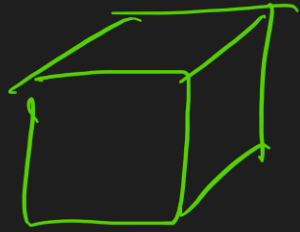
- CONS

- HIGH TEST-TIME COMPUTATIONAL COMPLEXITY, MEMORY INTENSIVE

- CURSE-OF-DIMENSIONALITY!

- CAN WE USE NEAREST NEIGHBOR FOR REGRESSION?

CURSE OF DIMENSIONALITY FOR NN

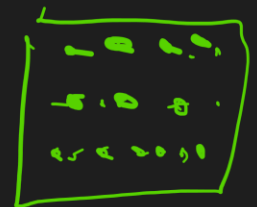


- ASSUME POINTS ARE IN THE d -DIMENSIONAL UNIT CUBE
 - HOW MANY TRAINING POINTS DO I NEED TO “COVER” THIS CUBE?

• E.G., FOR ANY $x \in [0,1]^d$, I WANT TO HAVE AT LEAST ONE TRAINING POINT x^i SUCH THAT $\|x - x^i\|_2 < 0.1$

- WE NEED 10^d TRAINING POINTS!

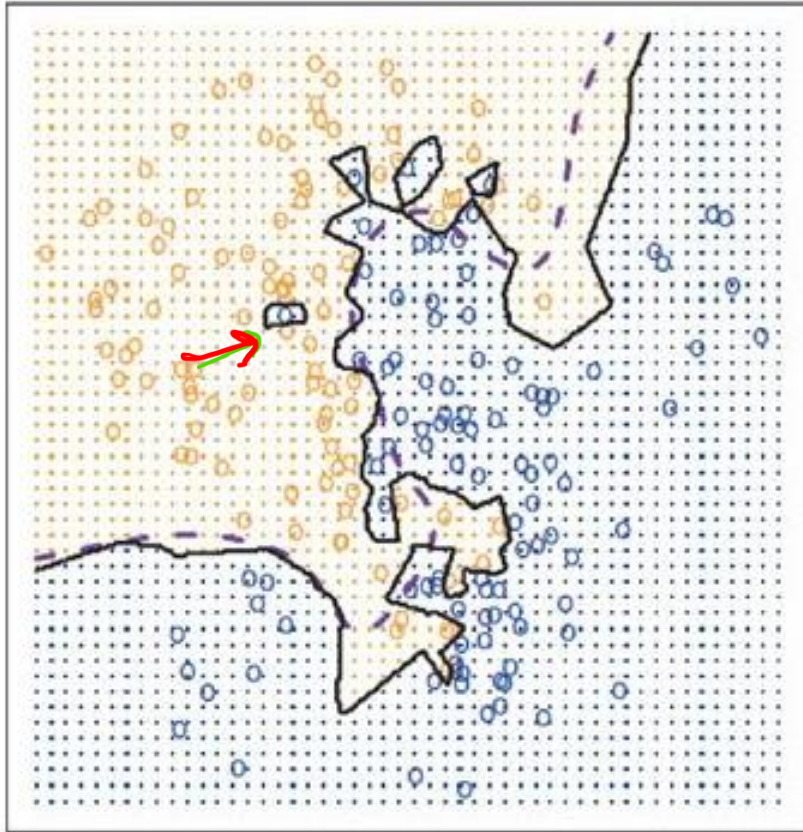
- NEAREST NEIGHBOR DOES NOT WORK WELL FOR HIGH-DIMENSIONAL DATA



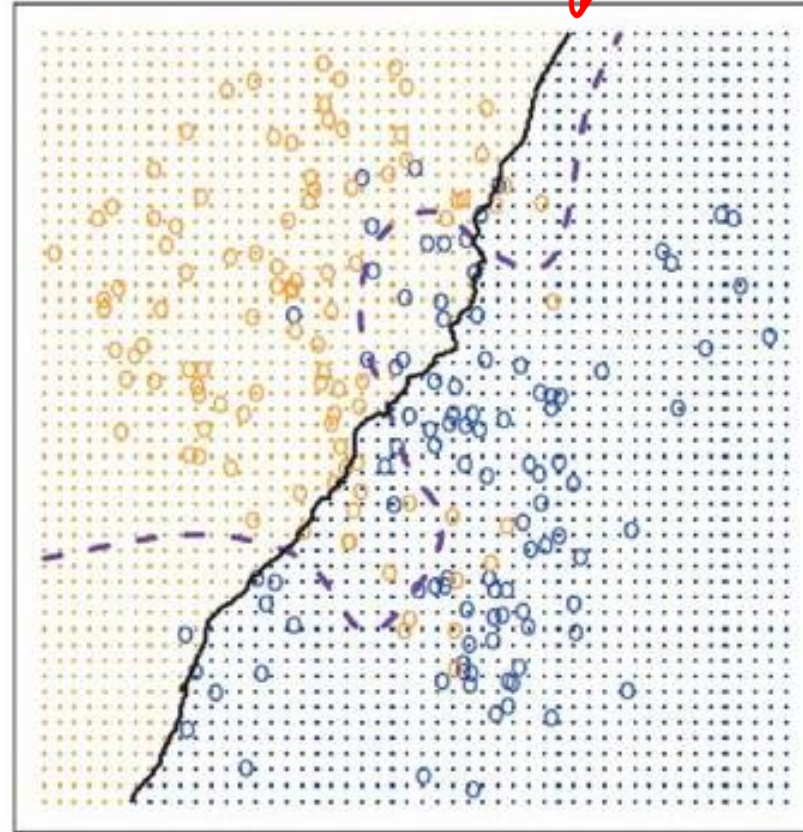
K-NEAREST NEIGHBOR

- $\hat{y}(x; Z) =$
 - FIND THE k CLOSEST POINTS TO x IN THE DATA SET
 - LET y^1, y^2, \dots, y^k BE THE LABELS OF THESE NEIGHBOR POINTS
 - OUTPUT THE **MAJORITY VOTE** AMONG y^i 'S

KNN: K=1

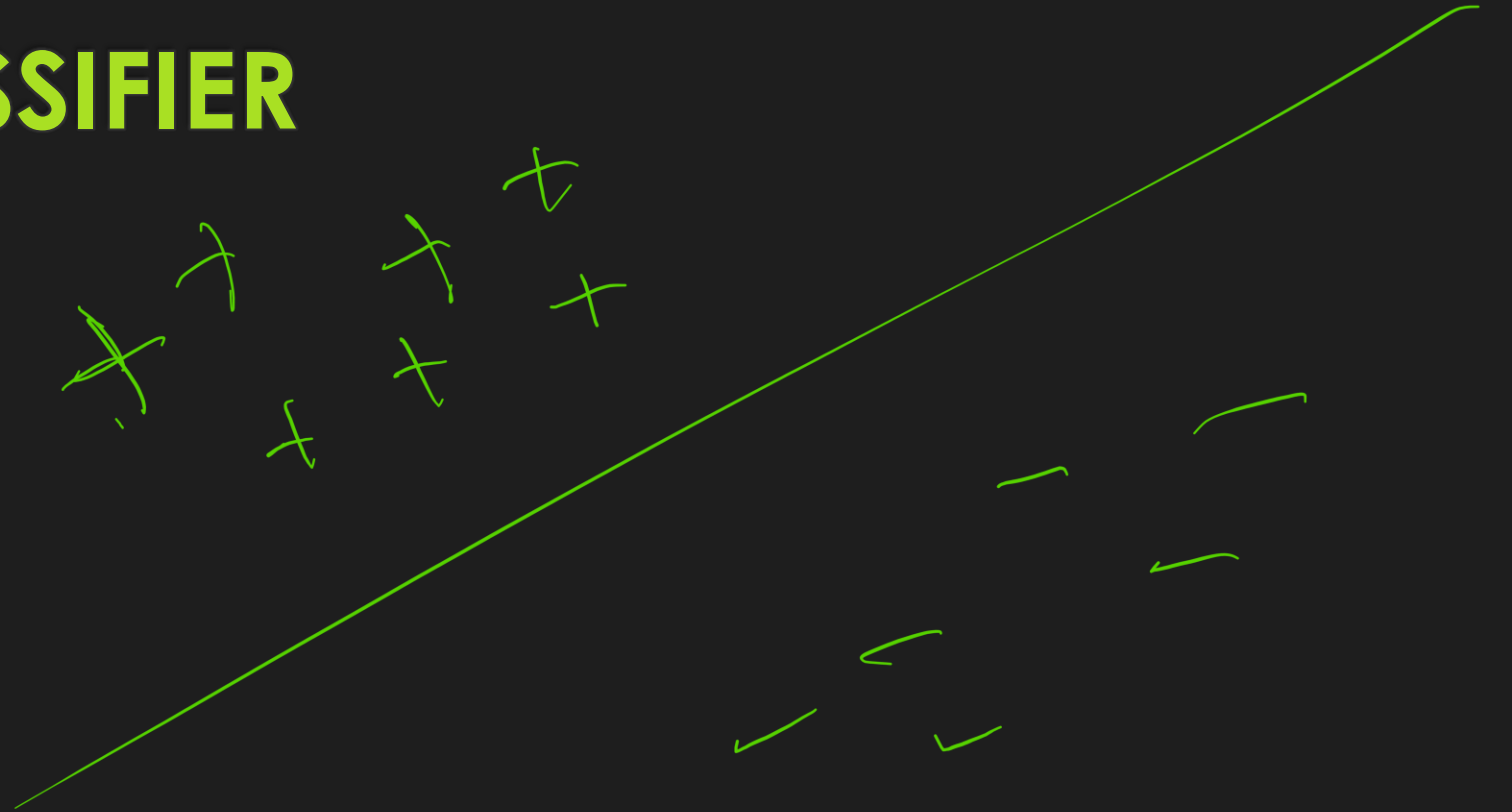


KNN: K=100



- MORE ROBUST, SMOOTHER DECISION BOUNDARY, HIGHER-TRAINING ERROR BUT LESS PRONE TO OVERFITTING
 - STILL CURSE OF DIMENSIONALITY

LINEAR CLASSIFIER



- $\hat{y}_w(x) = \text{sign}(W^T x) = 1_{W^T x \geq 0}$
- HOW TO FIND W GIVEN DATA SET Z ?

$$Y = \{0, 1\}$$

$$Y = \{-1, +1\}$$

LINEAR CLASSIFIERS

- EMPIRICAL RISK MINIMIZATION

• $\hat{W} = \underset{w}{\operatorname{argmin}} L_Z^{0-1}(\hat{y}_w) = \underset{w}{\operatorname{argmin}} \frac{1}{m} \sum \ell(\hat{y}_w(x^i), y^i)$

- COMPUTATIONAL COMPLEXITY FOR $d = 2$?

- HIGHER d ?



HARDNESS OF LINEAR CLASSIFICATION

- IN GENERAL, FINDING THE LINEAR SEPARATOR WITH MINIMUM CLASSIFICATION ERROR IS NP-HARD (WITH RESPECT TO d)
- UNLESS....
 - DATA IS LINEARLY SEPARABLE!
 - ..OR OPTIMIZE ANOTHER LOSS FUNCTION INSTEAD!
- CAN'T WE JUST GO INTO HIGHER DIMENSIONS TO MAKE THE DATA LINEARLY SEPARABLE?

LINEARLY SEPARABLE DATA

SURROGATE LOSS FUNCTIONS

- SO FAR, WE ASSUMED THE CLASSIFIER RETURNS A DISCRETE VALUE
 - E.G., $\hat{y}_w = \text{sign}(W^T x) \in \{0,1\}$
- WHAT IF THE CLASSIFIER'S OUTPUT IS CONTINUOUS
 - E.G., $\hat{y}_w = W^T x$
 - \hat{y} WILL CAPTURE THE "CONFIDENCE" OF THE CLASSIFIER TOO
- OTHER (CONTINUOUS) LOSS FUNCTIONS
 - MARGIN LOSS, CROSS-ENTROPY/NEGATIVE-LOG-LIKELIHOOD LOSS, ...
- POTENTIAL BENEFITS?
 - EASIER TO OPTIMIZE
 - MITIGATE OVERFITTING

