

INTRODUCTION TO
MACHINE LEARNING
COMPSCI 4ML3

LECTURE 24

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NO FREE LUNCH

- LARGER NETWORKS CAN FIT ANY DATA SET BUT
 - THE MORE FLEXIBLE THE MODEL THE MORE TRAINING DATA IS REQUIRED
 - COMPUTATIONAL COMPLEXITY

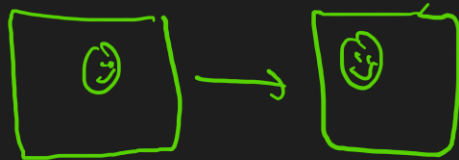
HOW CAN WE ADDRESS THESE DRAWBACKS?

- INCORPORATE DOMAIN KNOWLEDGE

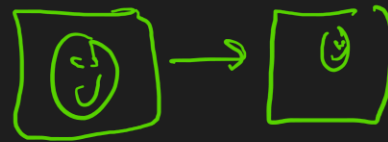
THE CASE OF IMAGE CLASSIFICATION

- IMAGE DATA HAS A LOT OF "STRUCTURE"
 - INVARIANCE

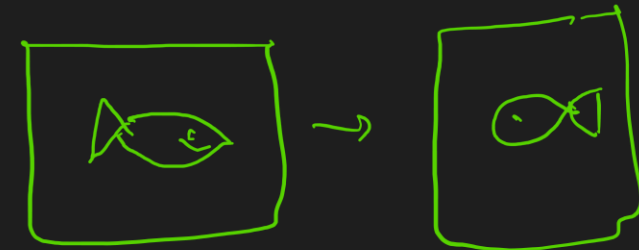
Translation



zoom in/out
(scale)



Reflection



Rotation



change of
perspective



- * lighting
- * Colour
- * Noise

THE CASE OF IMAGE CLASSIFICATION

- IMAGE DATA HAS A LOT OF "STRUCTURE"
 - LOCALITY



* spatial relationships
* nearby pixels are correlated

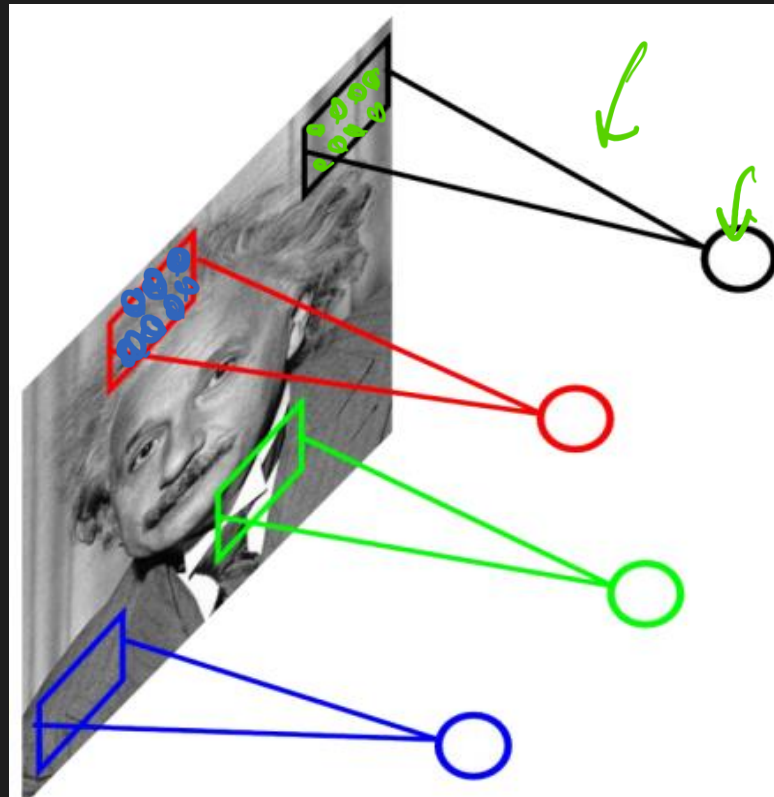
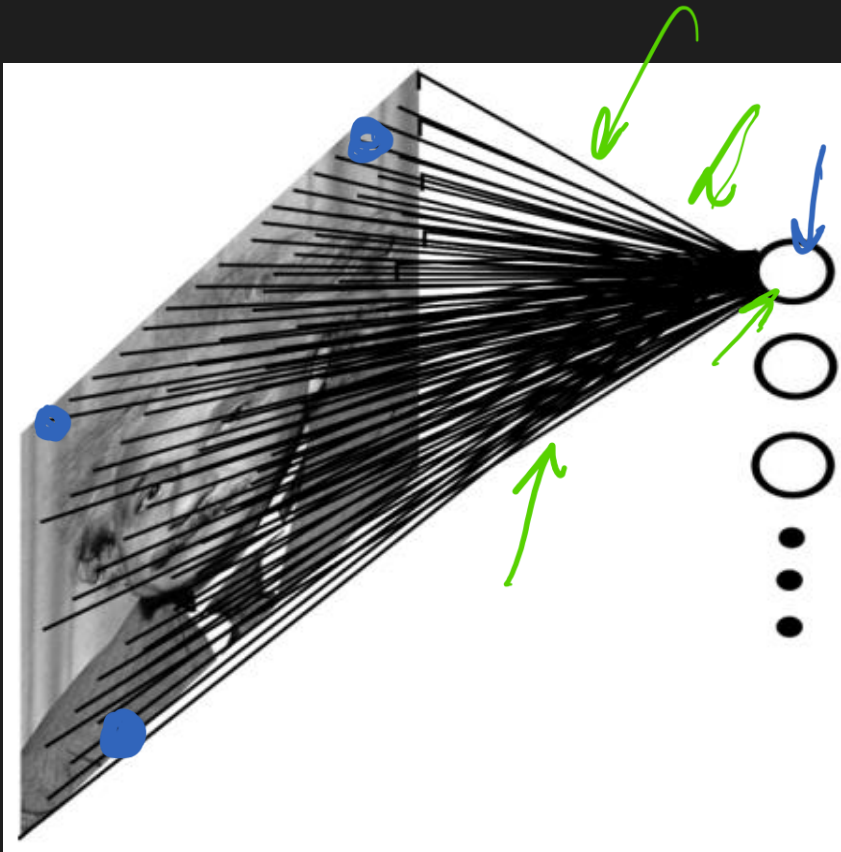
don't vectorize!

STRUCTURAL REGULARIZATION

- CAN WE USE THE PROPERTIES OF IMAGES TO REDUCE THE NUMBER OF PARAMETERS, WITHOUT COMPROMISING THE DISCRIMINATIVE POWER OF THEM?
- REGULARIZATION BY LITERALLY REDUCING THE NUMBER OF PARAMETERS

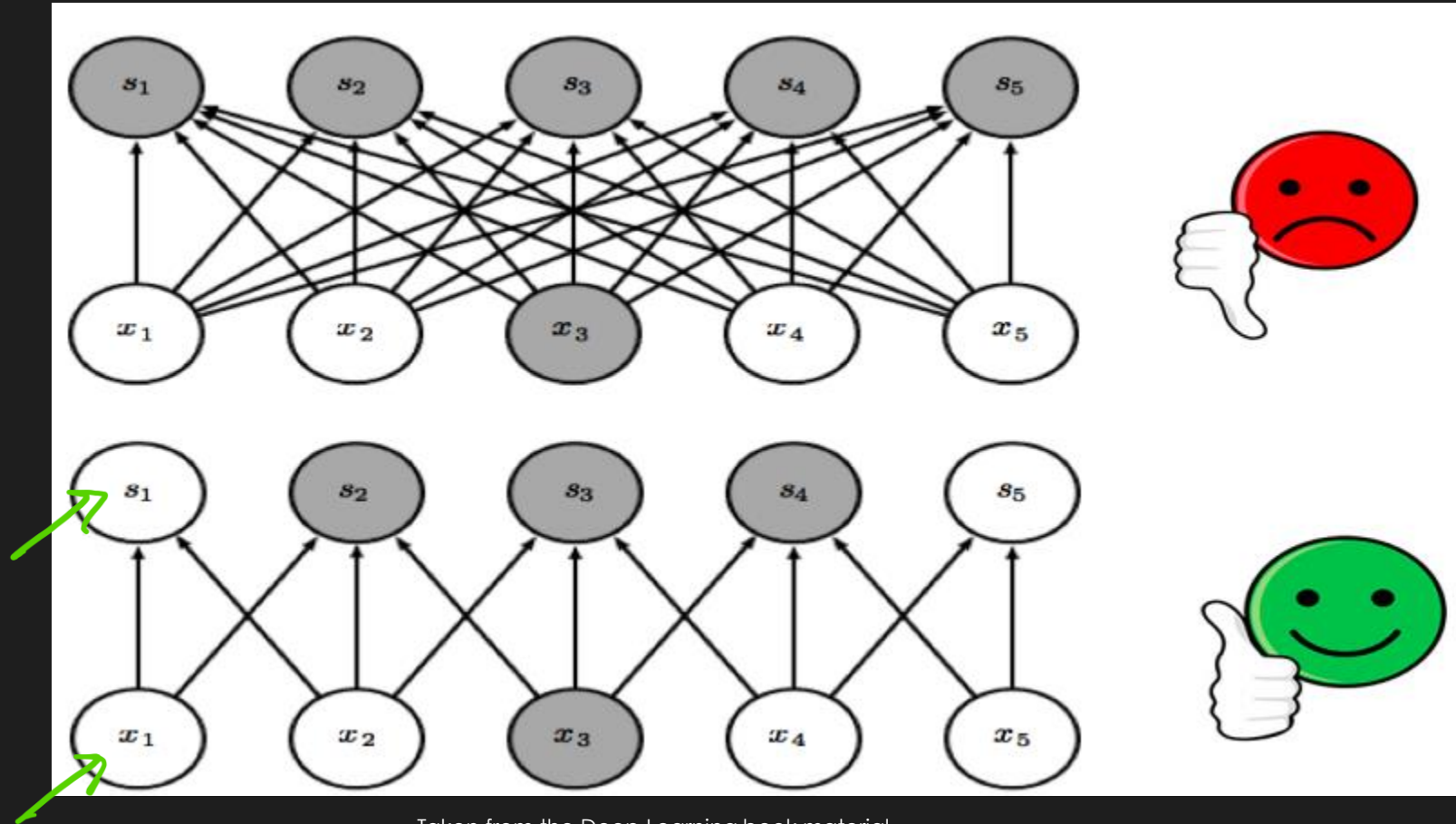
EXPLOITING LOCALITY

- SPARSE CONNECTIVITY RATHER THAN FULL CONNECTIVITY



Pictures taken from Ranzato slides

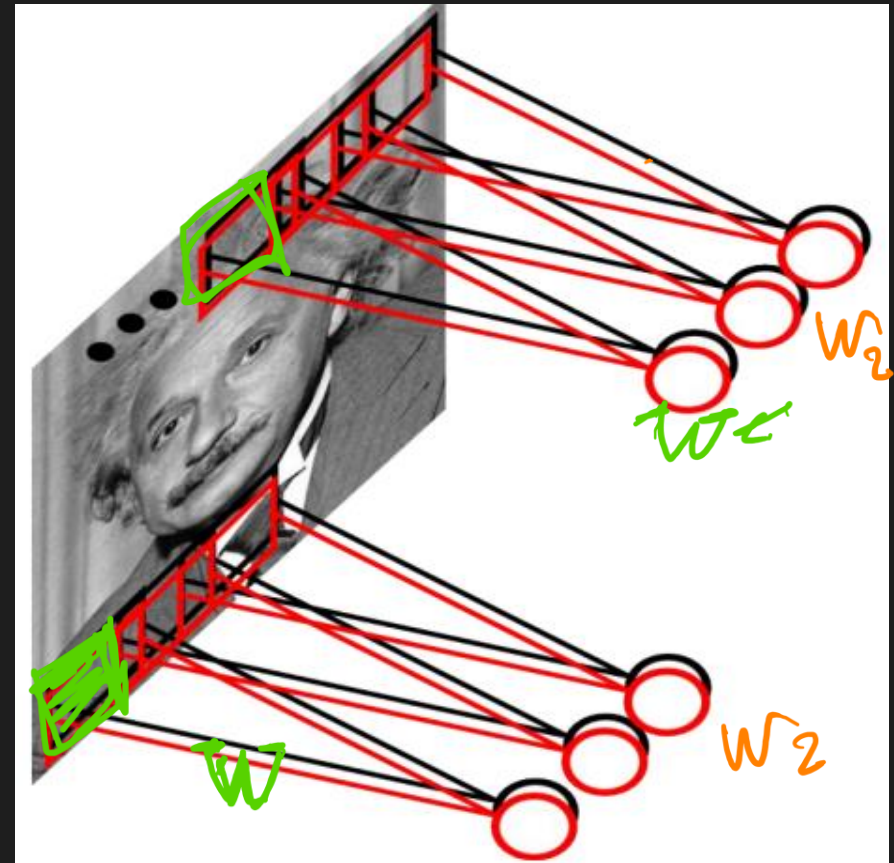
EXPLOITING LOCALITY



Taken from the Deep Learning book material

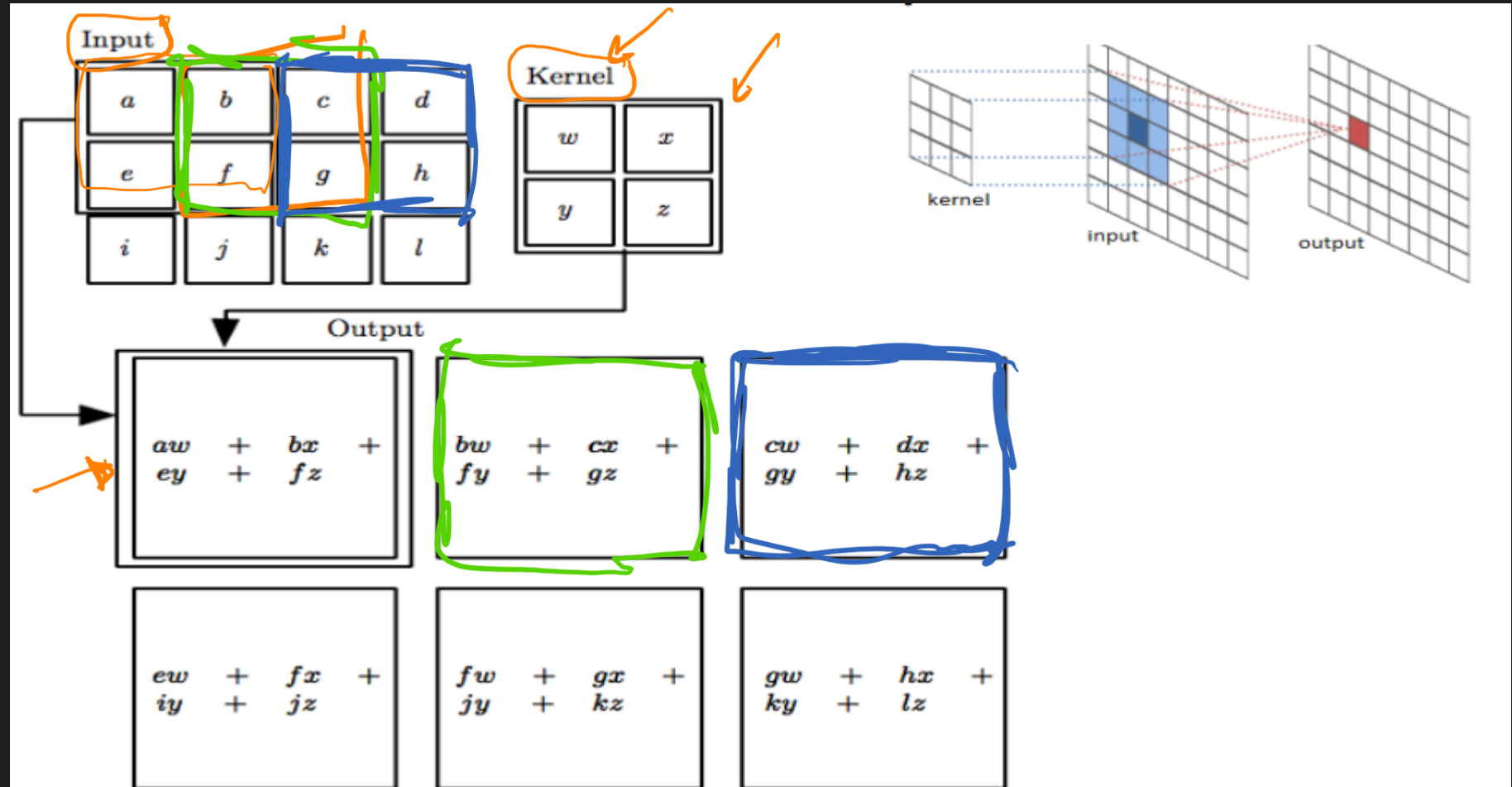
EXPLOITING INVARIANCE

- IF EXTRACTING A NOSE IS USEFUL IN ONE PART OF THE IMAGE, IT WILL BE USEFUL IN OTHER PARTS OF THE IMAGE AS WELL
- PARAMETER SHARING!



THE CONVOLUTION OPERATOR

TO BE MORE ACCURATE, THE KERNEL SHOULD BE FLIPPED.



CONVOLUTION OPERATOR

- 1-D CONVOLUTION

- $y = (x * w)$

- $y(i) = \sum_t x(t)w(i - t)$

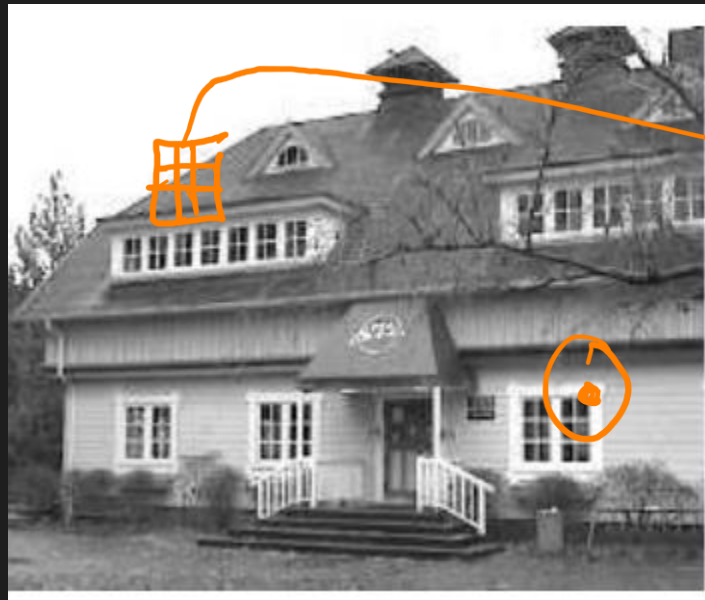
- 2-D CONVOLUTION

- $y = (x * w)$

- $y(i, j) = \sum_{t_1} \sum_{t_2} x(t_1, t_2)w(i - t_1, j - t_2)$

- USEFUL NOT ONLY FOR IMAGES, BUT FOR OTHER SIGNALS

BLUR



Kernel

1/9	1/9	1/9
1/9	1/9	1/9
1/9	1/9	1/9

Example taken from <http://aishack.in/tutorials/image-convolution-examples/>

GAUSSIAN BLUR

0	0	0	5	0	0	0
0	5	18	32	18	5	0
0	18	64	100	64	18	0
5	32	100	100	100	32	5
0	18	64	100	64	18	0
0	5	18	32	18	5	0
0	0	0	5	0	0	0



HORIZONTAL LINE



-1	-1	-1
2	2	2
-1	-1	-1



A KIND OF EDGE DETECTOR

-1	-1	-1
-1	8	-1
-1	-1	-1

Diagram illustrating a 3x3 kernel matrix used for edge detection. The matrix is:

$$\begin{bmatrix} -1 & -1 & -1 \\ -1 & 8 & -1 \\ -1 & -1 & -1 \end{bmatrix}$$

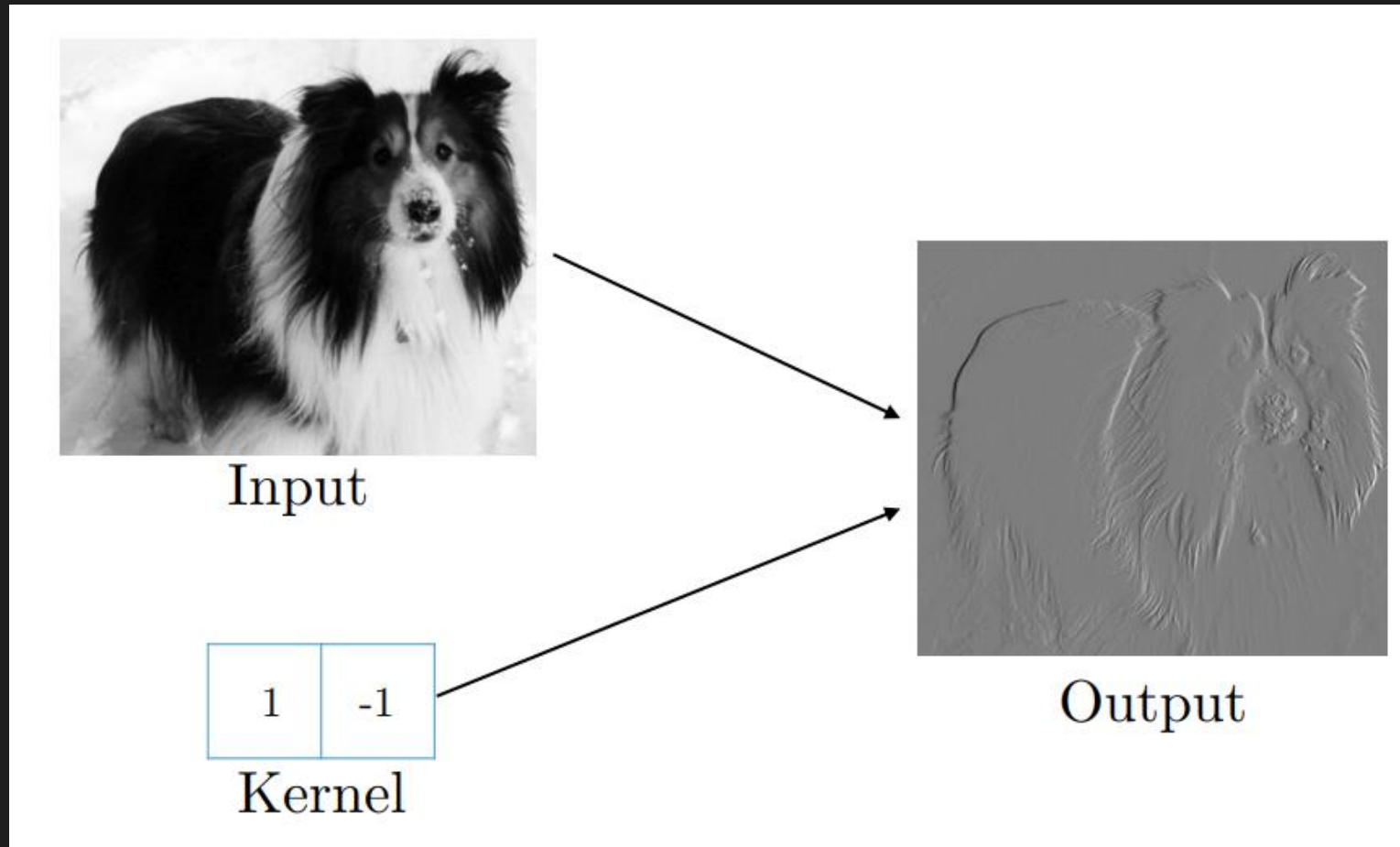
Orange arrows point to the top-left, top-middle, and bottom-left elements of the matrix, indicating the weights applied to the corresponding pixels in the input image.



A KIND OF EDGE DETECTOR

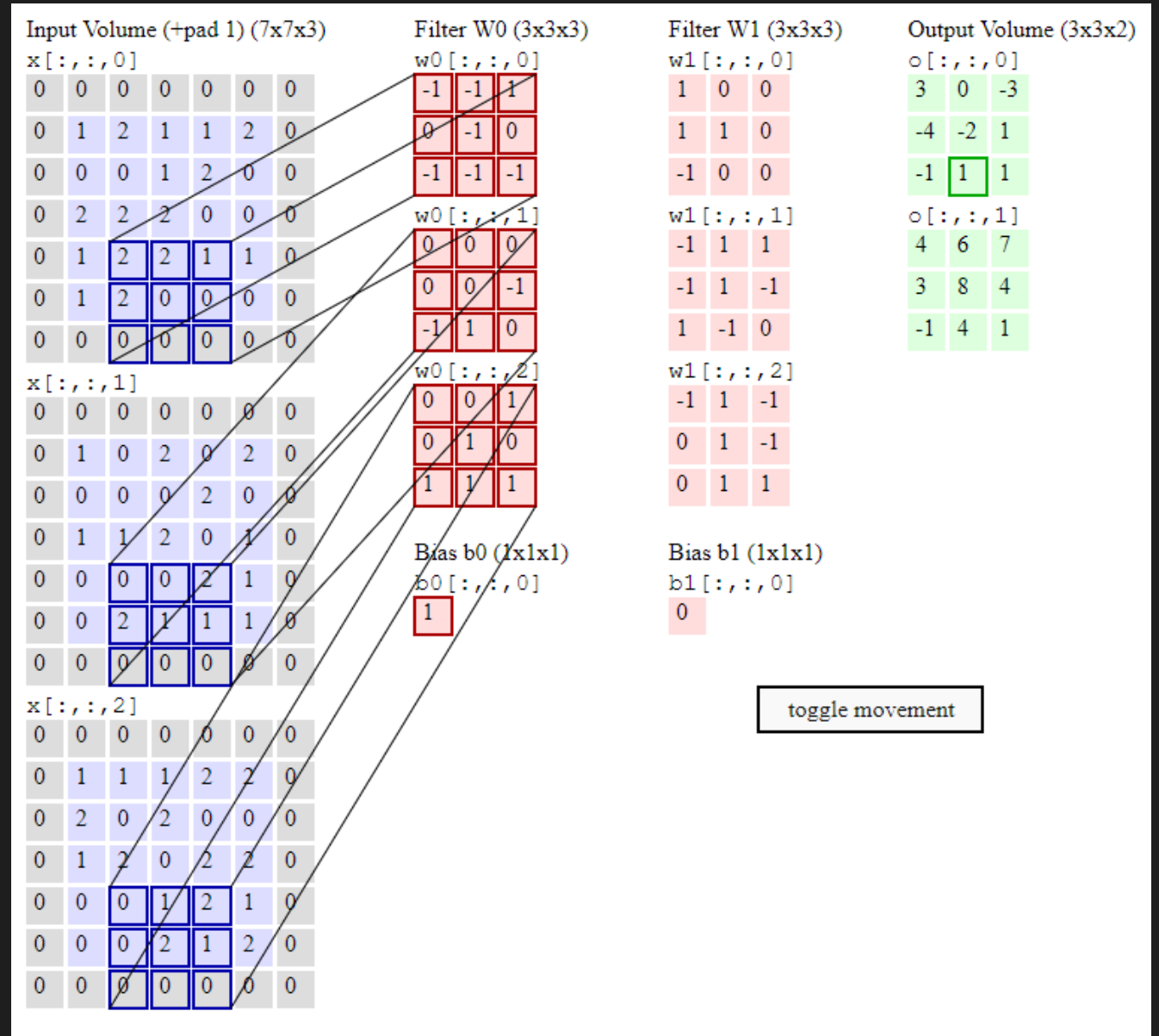
THE USE OF CONVOLUTION FOR IMAGE PROCESSING IS QUITE OLD

..BUT USING AN END-TO-END LEARNING APPROACH WHERE THE FILTERS/KERNELS ARE ALSO LEARNED IS THE POWER OF CONVOLUTIONAL NEURAL NETWORKS



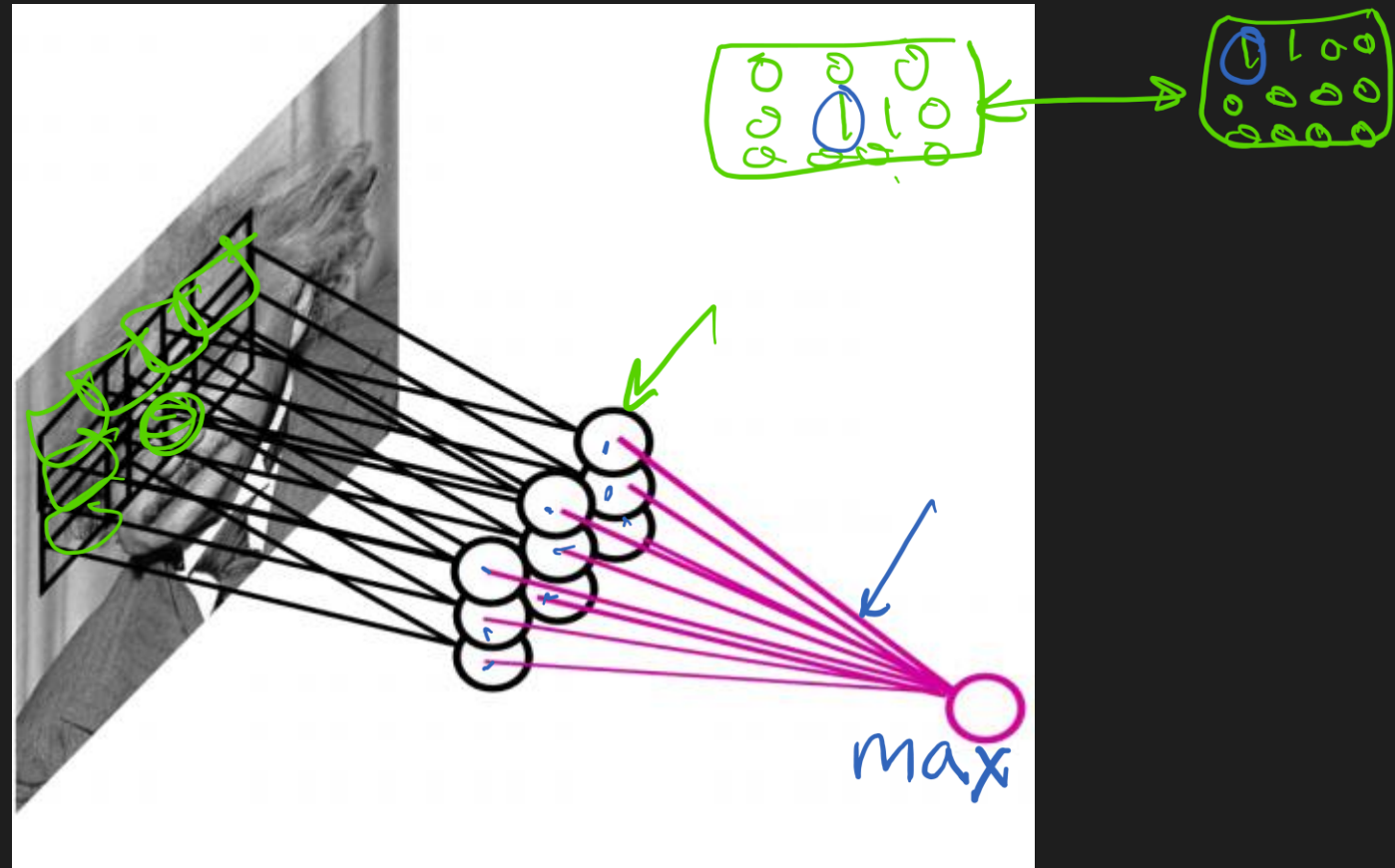
HTTP://CS231N.GITHUB.IO/CONVOLUTIONAL-NETWORKS/

- PADDING
- STRIDE
- CHANNEL
- KERNEL VS FILTER



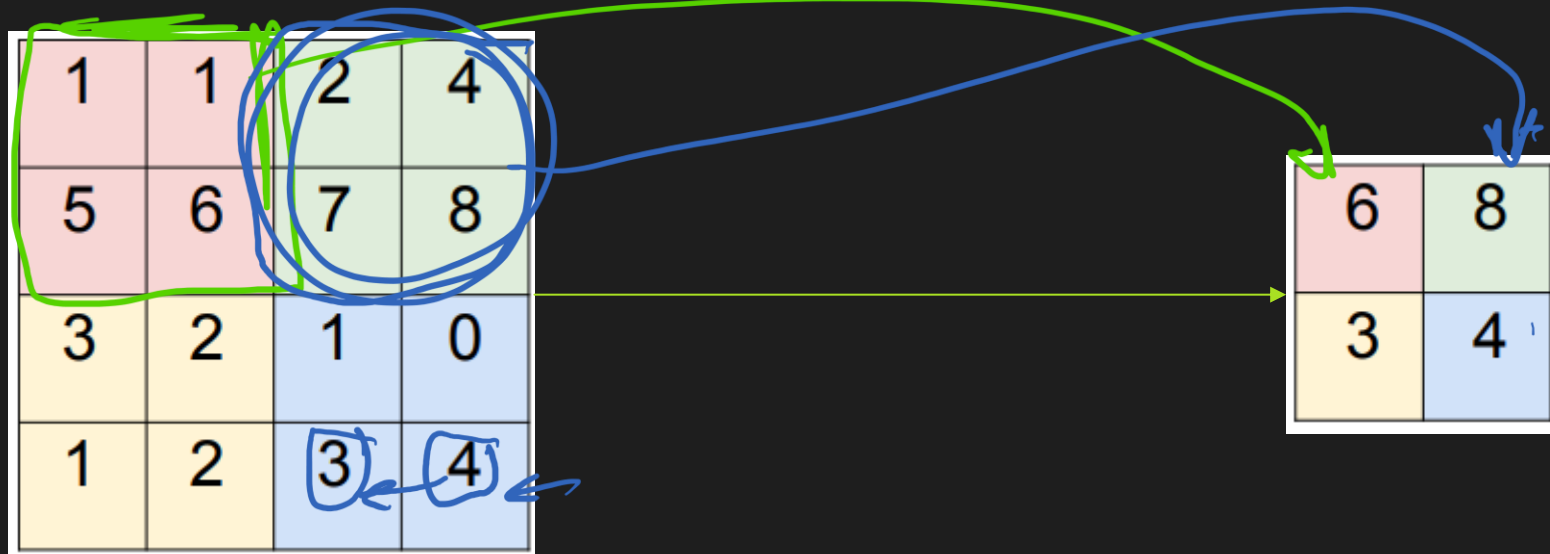
EXPLOITING LOCAL TRANSLATION-INVARIANCE

- IT DOES NOT MATTER EXACTLY WHICH OF THE SMALL PATCHES OF THE IMAGE INCLUDE A NOSE!
- MAX POOLING LAYER REDUCES THE NUMBER OF PARAMETERS



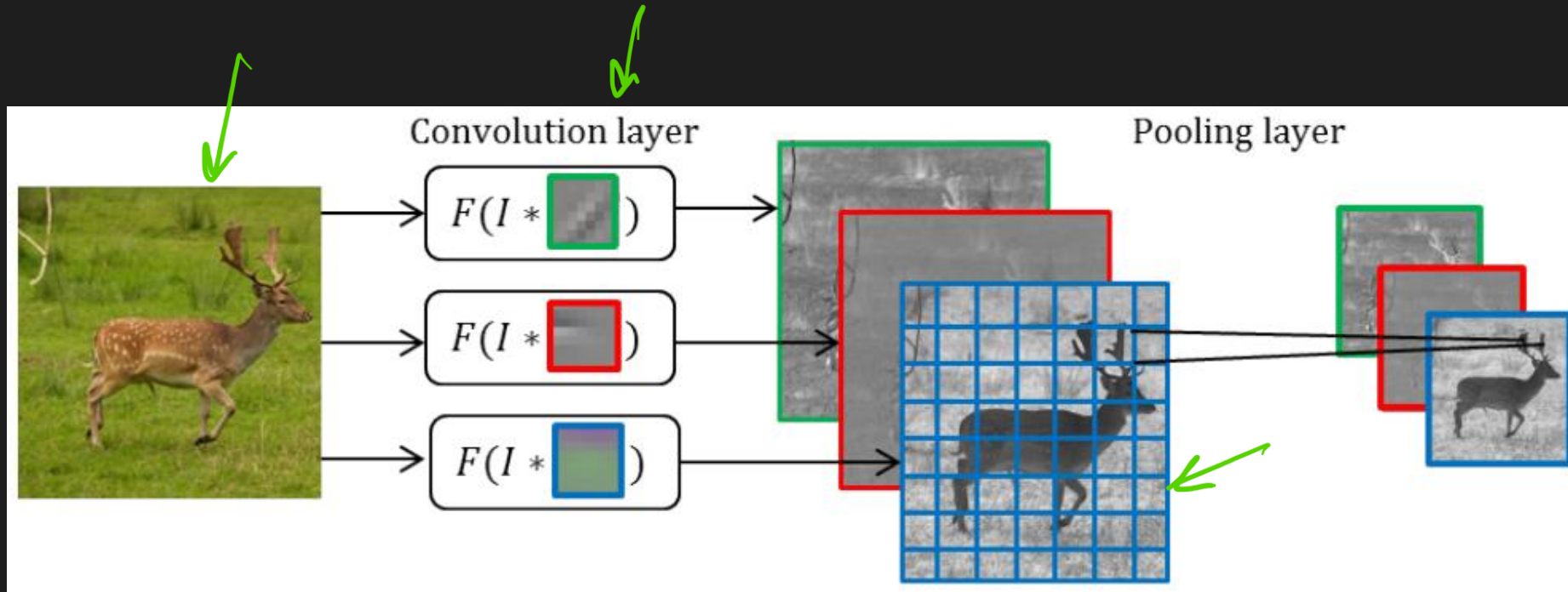
MAX POOLING

- 2X2 MAX POOLING
- STRIDE=2, NO PADDING

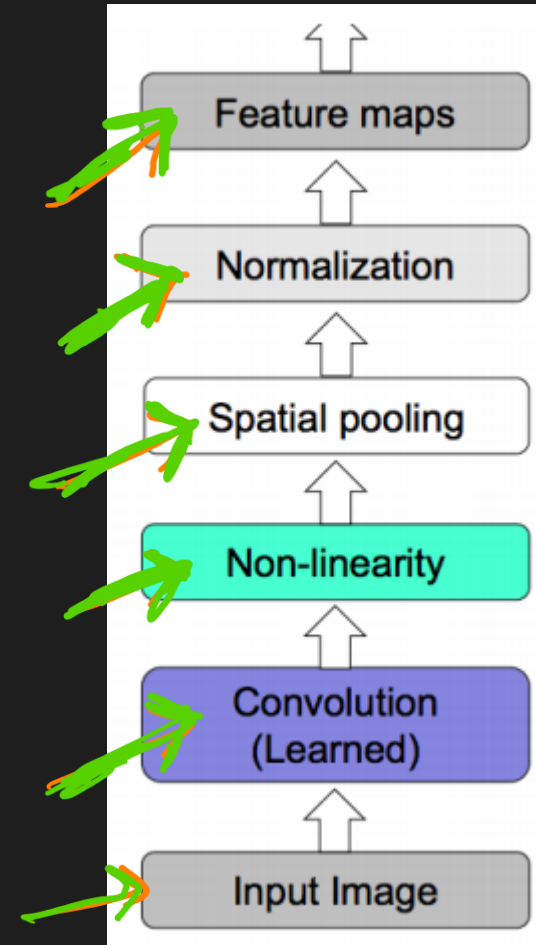


- STRIDE=1?

A FULL CONVOLUTIONAL LAYER

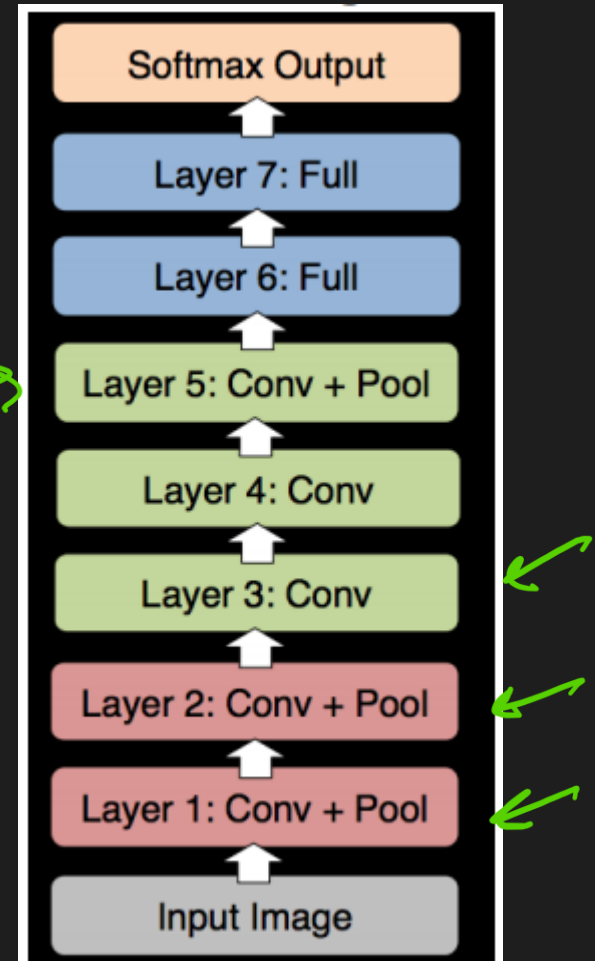


Taken from Barshan et al., "SCALABLE MULTI-NEIGHBORHOOD LEARNING FOR CONVOLUTIONAL NETWORKS"



BREAKTHROUGH IN IMAGENET

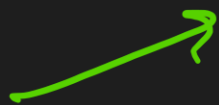
- IMAGENET CLASSIFICATION CHALLENGE
 - MILLIONS OF IMAGES
 - THOUSANDS OF CLASSES
- IN 2012, ALEXNET USED WON THE COMPETITION BY A HIGH MARGIN
 - $\sim 15\%$ ERROR COMPARED TO $\sim 25\%$ OF THE NEXT TEAM
 - THEY USED A CONVOLUTIONAL ARCHITECTURE
 - THEY USED GPUS FOR SPEEDUP
- CNNs BECAME VERY POPULAR



THINGS THE FIRST LAYER DETECTS



3RD LAYER



5TH LAYER

