# COMPSCI 4ML3 Tutorial 4: Review of Probability Theory

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Winter 2024

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 Review of Probability Theory

Elements

# Basic Elements I

- **Sample space**  $\Omega$ : The set of all possible outcomes.
- Event space  $\mathcal{F}$ : The set containing all possible subsets of outcomes. i.e., A collection of possible outcomes
- **Event** A: Any element of the event space.  $\forall A \in \mathcal{F}, A \subseteq \Omega$

For the event of rolling a dice:

•  $\Omega = \{1, 2, 3, 4, 5, 6\}$ 

• 
$$\mathcal{F} =$$

 $\{\{1\},\ldots,\{6\},\{1,2\},\ldots,\{5,6\},\{1,2,3\},\ldots,\{1,2,3,4,5,6\}\}$ 

• An example of an event is  $A = \{2, 3, 6\}$ 

Elements

# Basic Elements II

- Probability measure P: A function P : F → R that satisfies the following properties:
- $P(A) \ge 0, \forall A \in \mathcal{F}$
- $P(\Omega) = 1$
- For a collection of disjoint events A<sub>i</sub> i.e., (∀i ≠ j, A<sub>i</sub> ∩ A<sub>j</sub> = ∅) we have

$$\mathsf{P}(\bigcup_i A_i) = \sum_i \mathsf{P}(A_i)$$

Elements

# Probability Measure: Properties

- If  $A \subseteq B$ ,  $P(A) \leq P(B)$
- $P(A \cup B) \le P(A) + P(B)$ , which is called Union Bound
- $P(A \cap B) \leq \min(P(A), P(B))$
- $P(A^c) = 1 P(A)$
- For disjoint events  $A_1, \ldots, A_k$  such that  $\cup_{i=1}^k A_i = \Omega$

$$\sum_{i=1}^k P(A_i) = 1,$$

which is also called the law of total probability.

Elements

Conditional Probability and Independence

• The **conditional probability** P(A|B) is the probability of observing event A after the occurrence of B

$$P(A|B) = rac{P(A \cap B)}{P(B)}$$

 Two events A and B are independent iff P(A∩B) = P(A)P(B). i.e, observing B does not give any information about occurrence of A and P(A|B) = P(A)

Elements

# Conditional Probability and Independence

**Example**: Probability of a person's weight being y, given that her height is x.

$$P(\text{weight} = y | \text{height} = x)$$

These two features are correlated.

$$P( ext{weight} = 200 / b \mid ext{height} = 190 cm) = 0.2$$
  
 $P( ext{weight} = 200 / b \mid ext{height} = 140 cm) = 0.01$ 

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Elements

# Bayes' Rule

• For two events A and B

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$
$$P(B|A) = \frac{P(A \cap B)}{P(A)}$$

• This implies that

$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$
$$P(B|A) = \frac{P(A|B)P(B)}{P(A)}$$

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Elements

#### Chain Rule and Law of Total Probability

• For events  $A_1, \ldots, A_n$ , chain rule states that

$$P(A_n \cap \ldots \cap A_1) = P(A_n | A_{n-1} \cap \ldots \cap A_1) P(A_{n-1} \cap \ldots \cap A_1) =$$
$$P(A_1) \prod_{i=2}^n (A_i | \bigcap_{k=1}^{i-1} A_k)$$

 If B<sub>1</sub>,..., B<sub>n</sub> are finite partition of the sample space (i.e., ∀i ≠ j, B<sub>i</sub> ∩ B<sub>j</sub> = Ø and ∪<sup>n</sup><sub>i=1</sub>B<sub>i</sub> = Ω), the law of total probability states that for an event A

$$P(A) = \sum_{i=1}^{n} P(A \cap B_i) = \sum_{i=1}^{n} P(A|B_i)P(B_i)$$

**Random Variables** 

# Random Variables

A real-valued random variable X is a mapping from sample space to real values, i.e.,  $X : \Omega \to \mathbb{R}$ , which assigns to each element  $\omega \in \Omega$  a real value X(w)

A random variable helps us describe some functions of observed events

- We usually denote random variables with capital letters X(ω) and simply denote it with X
- We usually use small letters for the value that a random variable may take. i.e., we write X = x instead of X(ω) = x

**Random Variables** 

# Random Variables: Example

**Example**: We toss coin for 20 times. What is the probability that we observe 6 heads?

- Sample space  $\Omega$  can be defined as the sequences of heads and tails with length 20
- Random variable X is a function that assigns to each sequence ω ∈ Ω the number of heads in that sequence. i.e., X(ω) = number of heads in ω
- We are interested in finding  $P(X(\omega) = 6)$  or simply P(X = 6)

Random Variables

# Random Variables

• A random variable that only takes finite number of values is called a **discrete random variable** 

• The probability that a random variable X takes value x is

$$P(X = x) := P(\{\omega \in \Omega : X(\omega) = x\})$$

- A random variable that can take infinite number of values is called a **continuous random variable** 
  - The probability that a random variable X takes values between a and b is

$$P(a \leq X \leq b) := P(\{\omega \in \Omega : a \leq X(\omega) \leq b\})$$

CDF

# Cumulative Distribution Function

For a random variable X, we can define  $P(X \le x)$  as a function of x:

The Cumulative Distribution Function (CDF) is a function F<sub>X</sub>(x) : ℝ → [0, 1] that is defined as

$$F_X(x) := P(X \leq x)$$

**Properties:** 

CDF

### Cumulative Distribution Function

#### Example:



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PMF

# Probability Mass Function

For a <u>discrete</u> random variable, the **Probability Density Function(PMF)**  $p_X(x) : \mathbb{R} \to [0, 1]$  is a function that returns the probability of a random variable taking a specific value

$$p_X(x) := P(X = x)$$

#### **Properties:**

- $0 \le p_X(x) \le 1$
- $\sum_{x \in \mathbb{D}} p_X(x) = 1$ , where  $\mathbb{D}$  is the set of all possible values that X can take.
- $P(X \in A) = P(\{\omega : X(\omega) \in A\}) = \sum_{x \in A} p_X(x)$

PMF

# Probability Mass Function

#### Example:



# Probability Density Function

For a <u>continuous</u> random variable, we are interested in  $P(x \le X \le x + \Delta x)$  when  $\Delta \rightarrow 0$ . If  $F_X(x)$  is differentiable everywhere, the **Probability Density Function (PDF)**  $f_X(x)$  is the derivative of the CDF function

$$f_X(x) := \frac{dF_X(x)}{dx}$$

- $P(x \le X \le x + \Delta x) \approx f_X(x)\Delta x$
- Unlike PMF, f<sub>X</sub>(x) is not the probability that the random variable X takes a value x. i.e., f<sub>X</sub>(x) ≠ P(X = x). In fact, for a continuous distribution, the probability that the random variable takes a specific value is zero. i.e, P(X=x)=0

PDF

# Probability Density Function

#### Example:



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# PDF: Properties

• 
$$f_X(x) \ge 0$$
  
•  $\int_{-\infty}^{\infty} f_X(x) = 1$ 

• 
$$F_X(x) = \int_{-\infty} f_X(x) dx$$

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Expectation and Variance

### Expectation

For a *discrete* random variable with PMF p<sub>X</sub>(x) and a function g(x) : ℝ → ℝ, g(X) can be considered as a random variable and the **expectation** or **expected value** of g(X) is defined as

$$\mathbb{E}[g(X)] = \sum_{x \in \mathbb{D}} g(x) p_X(x)$$

 For a continuous random variable with PDF f<sub>X</sub>(x), the expectation or expected value of g(X) is defined as

$$\mathbb{E}[g(X)] = \int_{-\infty}^{\infty} g(x) f_X(x) dx$$

Expectation and Variance

### Mean and Variance

Setting g(x) = x, the mean of a random variable X is defined as

$$\mu = \mathbb{E}[X] = \int_{-\infty}^{\infty} x f_X(x) dx$$

• The **variance** of a random variable *X* is a measure of how concentrated the random variable is around its mean

$$\sigma^2 = \operatorname{Var} = \mathbb{E}[(X - \mathbb{E}[X])^2] = \mathbb{E}[X^2 + (\mathbb{E}[X])^2 - 2X\mathbb{E}[X]]$$
$$= \mathbb{E}[X^2] + (\mathbb{E}[X])^2 - 2\mathbb{E}[X\mathbb{E}[X]] = \mathbb{E}[X^2] - (\mathbb{E}[X])^2$$

Expectation and Variance

#### Mean and Variance: Example I

**Example** Find the mean and variance of rolling a dice with equal probability for each face

$$\mu = \mathbb{E}[X] = \sum_{i=1}^{6} iP(X=i) = \sum_{i=1}^{6} i\frac{1}{6} = \frac{21}{6} = 3.5$$
$$\sigma^{2} = \mathbb{E}[(X-\mu)^{2}] = \sum_{i=1}^{6} (i-3.5)^{2}P(X=i)$$
$$= \sum_{i=1}^{6} (i-3.5)^{2}\frac{1}{6} = \frac{35}{12} \approx 2.92$$

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Expectation and Variance

### Mean and Variance: Example II

Example Find the mean and variance of a random variable with PDF  $f_X(x) = 3x^2$ ,  $0 \le x \le 1$ 

$$\mu = \mathbb{E}[X] = \int_{-\infty}^{\infty} x f_X(x) dx = \int_0^1 x f_X(x) dx = \int_0^1 3x^3 dx = \frac{3x^4}{4} \Big|_0^1 = \frac{3}{4}$$
$$\sigma^2 = \mathbb{E}[(X - \mu)^2] = \int_{-\infty}^{\infty} (x - \mu)^2 f_X(x) dx = \int_0^1 (x - \frac{3}{4})^2 3x^2 dx$$
$$= \int_0^1 (x - \frac{3}{4})^2 3x^2 dx = \frac{3}{16}$$

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Density Functions

- $\mathbb{E}[c] = c, \forall c \in \mathbb{R}$
- $\mathbb{E}[cg(X)] = c\mathbb{E}[g(X)], \forall c \in \mathbb{R}$
- $\mathbb{E}[f(X) + g(X)] = \mathbb{E}[f(X)] + \mathbb{E}[g(X)]$

Expectation: Properties

Expectation and Variance

Expectation and Variance

# Variance: Properties

• 
$$Var(c) = 0, \forall c \in \mathbb{R}$$

• 
$$Var(f(X) + c) = Var(f(X)), \forall c \in \mathbb{R}$$

• 
$$Var(cf(X)) = c^2 Var(f(X)), \forall c \in \mathbb{R}$$

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Discrete Random Variables

### Discrete Random Variables: Bernoulli

• 
$$X \sim \text{Bernoulli}(p)$$
, where  $0 \le p \le 1$ 

$$p_X(x) = \begin{cases} p & x = 1\\ 1 - p & x = 0 \end{cases}$$

Discrete Random Variables

#### Discrete Random Variables: Binomial

•  $X \sim \text{Binomial}(n, p)$ , where  $0 \le p \le 1$ 

$$p_X(x) = \binom{n}{x} p^x (1-p)^{n-x}$$

Discrete Random Variables

# Discrete Random Variables: Poisson

• 
$$X \sim \text{Possion}(\lambda)$$
, where  $\lambda > 0$ 

$$p_X(x) = \frac{e^{-\lambda}\lambda^x}{x!}$$

• 
$$\mathbb{E}[X] = \lambda$$
  
•  $Var(X) = \lambda$ 

Continuous Random Variables

### Continuous Random Variables: Uniform

• 
$$X \sim U_{[a,b]}$$
, where  $a \leq b$ 

$$f_X(x) = \begin{cases} rac{1}{b-a} & x \in [a,b] \\ 0 & ext{otherwise} \end{cases}$$

• 
$$\mathbb{E}[X] = \frac{b+a}{2}$$
  
•  $Var(X) = \frac{(b-a)^2}{12}$ 

Continuous Random Variables

### Continuous Random Variables: Exponential

• 
$$X \sim \text{Exponential}(\lambda)$$
, where  $\lambda > 0$ 

$$f_X(x) = \lambda e^{-\lambda x}$$

• 
$$\mathbb{E}[X] = \frac{1}{\lambda}$$
  
•  $\operatorname{Var}(X) = \frac{1}{\lambda^2}$ 

Continuous Random Variables

### Continuous Random Variables: Gaussian/Normal

• 
$$X \sim \mathcal{N}(\mu, \sigma^2)$$
  
 $p_X(x) = \frac{1}{\sqrt{2\pi\sigma}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$ 

• 
$$\mathbb{E}[X] = \mu$$
  
•  $Var(X) = \sigma^2$ 

# Joint Distribution

Example:

X = image :



Y = label (1 if image contains cat and 0 otherwise) What is the probability of an image contains a cat?

$$P(X = \text{image}, Y = 0) =?$$
$$P(X = \text{image}, Y = 1) =?$$

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Joint CDF

# Joint Cumulative Distributions

It happens that we need to consider two random variables X and Y together and discuss X and Y at the same time during a random experiment.

• The **joint cumulative distribution** function for random variables *X* and *Y* is defined as

$$F_{X,Y}(x,y) = P(X \le x, Y \le y)$$

• The marginal CDFs can be found by

$$F_X(x) = \lim_{y \to \infty} F_{X,Y}(x, y)$$
$$F_Y(y) = \lim_{x \to \infty} F_{X,Y}(x, y)$$

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Joint CDF

# Joint CDF: Properties

• 
$$0 \leq F_{X,Y}(x,y) \leq 1$$

• 
$$\lim_{x,y\to\infty} F_{X,Y}(x,y) = 1$$

• 
$$\lim_{x,y\to-\infty}F_{X,Y}(x,y)=0$$

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Joint PMF

# Joint Probability Mass Function

• The joint probability mass function for *discrete* random variables X and Y is defined as

$$p_{X,Y}(x,y) = P(X = x, Y = y)$$

• The marginal PMFs can be found by

$$p_X(x) = \sum_{y \in \mathbb{D}_y} p_{X,Y}(x,y)$$
  
 $p_Y(y) = \sum_{x \in \mathbb{D}_y} p_{X,Y}(x,y)$ 

Joint PMF

### Joint PMF: Properties

• 
$$0 \leq p_{X,Y}(x,y) \leq 1$$

• 
$$\sum_{x \in \mathbb{D}_x, y \in \mathbb{D}_y} p_{X,Y}(x,y) = 1$$

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Joint PDF

# Joint Probability Density Function

 If the joint CDF is differentiable everywhere in x and y, the joint probability density function for *continuous* random variables X and Y is defined as

$$f_{X,Y}(x,y) = \frac{\partial^2 F_{X,Y}(x,y)}{\partial x \partial y}$$

• The marginal PDFs can be found by

$$f_X(x) = \int_{-\infty}^{\infty} f_{X,Y}(x,y) dy$$
$$f_Y(y) = \int_{-\infty}^{\infty} f_{X,Y}(x,y) dx$$

Joint PDF

# Joint PDF: Properties

• 
$$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f_{X,Y}(x,y) dx dy = 1$$

• 
$$\int \int_A f_{X,Y}(x,y) dx dy = P((X,Y) \in A)$$

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Conditional PMF and PDF

# Conditional Distributions

 Conditional PMF refers to the probability distribution over X when we know that Y has taken a certain value (if p<sub>Y</sub>(y) ≠ 0)

$$p_{X|Y}(x|y) = P(X = x|Y = y) = \frac{P(X = x, Y = y)}{P(Y = y)} = \frac{p_{X,Y}(x,y)}{p_Y(y)}$$

• Conditional PDF is defined as (if  $f_Y(y) \neq 0$ )

$$f_{X|Y}(x|y) = \frac{f_{X,Y}(x,y)}{f_Y(y)}$$

Independence

# Independent Random Variables

Two random variables X and Y are independent iff

$$F_{X,Y}(x|y) = F_X(x)F_Y(y), \forall x, y$$

• If two discrete random variables X and Y are independent

$$p_{X,Y}(x,y) = p_X(x)p_Y(y), \forall x, y$$
$$p_{X|Y}(x|y) = p_X(x), \forall x, y \text{ such that } p_Y(y) \neq 0$$

• If two continuous random variables X and Y are independent

$$f_{X,Y}(x,y) = f_X(x)f_Y(y), \forall x, y$$
  
$$f_{X|Y}(x|y) = f_X(x), \forall x, y \text{ such that } f_Y(y) \neq 0$$

Bayes' Rule

# Bayes' Rule for Joint Probability Distribution

• For two *discrete* random variables X and Y

$$p_{X|Y}(x|y) = \frac{p_{Y|X}(y|x)p_X(x)}{p_Y(y)}$$

• For two continuous random variables X and Y

$$f_{X|Y}(x|y) = \frac{f_{Y|X}(y|x)f_X(x)}{f_Y(y)}$$

Expectation and Covariance

# Expectation of Joint Distributions

For discrete random variables X and Y with joint PMF p<sub>X,Y</sub>(x, y) and a function g(x, y) : ℝ<sup>2</sup> → ℝ, g(X, Y) can be considered as a random variable and the expectation or expected value of g(X, Y) is defined as

$$\mathbb{E}[g(X,Y)] = \sum_{x \in \mathbb{D}_x} \sum_{y \in \mathbb{D}_y} g(x,y) p_{X,Y}(x,y)$$

For continuous random variables X and Y with joint PDF f<sub>X,Y</sub>(x, y), the expectation or expected value of g(X, Y) is defined as

$$\mathbb{E}[g(X,Y)] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x,y) f_{X,Y}(x,y) dx dy$$

Expectation and Covariance

# Covariance of Joint Distributions

• The covariance of two random variables X and Y is defined as

$$Cov(X, Y) = \mathbb{E}[(X - \mathbb{E}[X])(Y - \mathbb{E}[Y])]$$
  
=  $\mathbb{E}[XY - Y\mathbb{E}[X] - X\mathbb{E}[Y] + \mathbb{E}[X]\mathbb{E}[Y]]$   
=  $\mathbb{E}[XY] - \mathbb{E}[X]\mathbb{E}[Y] - \mathbb{E}[X]\mathbb{E}[Y] + \mathbb{E}[X]\mathbb{E}[Y]$   
=  $\mathbb{E}[XY] - \mathbb{E}[X]\mathbb{E}[Y]$ 

 If Cov(X, Y) = 0, two random real-valued variables are called uncorrelated.

Expectation and Covariance

#### Expectation and Covariance: Properties

- $\mathbb{E}[f(X,Y)+g(X,Y)] = \mathbb{E}[f(X,Y)] + \mathbb{E}[g(X,Y)]$
- $\operatorname{Var}(X + Y) = \operatorname{Var}(X) + \operatorname{Var}(Y) + 2\operatorname{Cov}(X, Y)$
- If X and Y are independent, Cov(X, Y) = 0
- If X and Y are independent,  $\mathbb{E}[f(X)g(Y)] = \mathbb{E}[f(X)]\mathbb{E}[g(Y)]$

Multivariate distributions

#### Generalized Joint Distribution for *n* Variables

For *n* random variables  $X_1, \ldots, X_n$ 

• Joint CDF is defined as

$$F_{X_1,\ldots,X_n}(x_1,\ldots,x_n)=P(X_1\leq x_1,\ldots,X_n\leq x_n)$$

• For discrete random variables joint PMF is defined as

$$p_{X_1,...,X_n}(x_1,...,x_n) = P(X_1 = x_1,...,X_n = x_n)$$

• For continuous random variables joint PDF is defined as

$$f_{X_1,\ldots,X_n}(x_1,\ldots,x_n)=\frac{\partial^n F_{X_1,\ldots,X_n}(x_1,\ldots,x_n)}{\partial x_1\ldots\partial x_n}$$

Multivariate distributions

### Joint Distribution for *n* Variables

For *n* randaom variable X<sub>1</sub>,..., X<sub>n</sub>
Marginal PDFs can be derived by

Marginal PDFs can be derived by

$$f_{X_1}(x_1) = \int_{-\infty}^{\infty} \ldots \int_{-\infty}^{\infty} f_{X_1,\ldots,X_n}(x_1,\ldots,x_n) dx_2 \ldots dx_n$$

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$$P((X_1,\ldots,X_n)\in A)=\int\ldots\int_A f_{X_1,\ldots,X_n}(x_1,\ldots,x_n)dx_1\ldots dx_n$$

• X<sub>1</sub>,..., X<sub>n</sub> are mutually independent iff

$$f_{X_1,...,X_n}(x_1,...,x_n) = \prod_{i=1}^n f_{X_i}(x_i)$$

Review of Probability Theory

Random Vectors

### Random Vectors

When dealing with *n* random variables, we can consider them as a random vector  $X = [X_1, \ldots, X_n]^T$ 

For the random vector X, the expectation is in the form of a vector. For a function g : ℝ<sup>n</sup> → ℝ<sup>m</sup>

$$\mathbb{E}[g(X)] = egin{bmatrix} \mathbb{E}[g_1(X)] \ dots \ \mathbb{E}[g_m(X)] \end{bmatrix}$$

• The mean vector is  $\mu = \mathbb{E}[X] = [\mathbb{E}[X_1], \dots, \mathbb{E}[X_n]]^T$ 

Random Vectors

# Covariance Matrix

For a random vector  $X \in \mathbb{R}^n$ , its covariance matrix  $\Sigma \in \mathbb{R}^{n \times n}$  is a symmetric positive semidefinite matrix, where  $\Sigma_{i,j} = \text{Cov}(X_i, X_j)$ 

$$\Sigma = \begin{bmatrix} \operatorname{Cov}(X_1, X_1) & \operatorname{Cov}(X_1, X_2) & \dots & \operatorname{Cov}(X_1, X_n) \\ \operatorname{Cov}(X_2, X_1) & \operatorname{Cov}(X_2, X_2) & \dots & \operatorname{Cov}(X_2, X_n) \\ \vdots & \vdots & \ddots & \vdots \\ \operatorname{Cov}(X_n, X_1) & \operatorname{Cov}(X_n, X_2) & \dots & \operatorname{Cov}(X_n, X_n) \end{bmatrix} \\ = \mathbb{E}[(X - \mathbb{E}[X])(X - \mathbb{E}[X])^T] = \mathbb{E}[XX^T] - \mathbb{E}[X]\mathbb{E}[X]^T$$

Note  $Cov(X_i, X_i) = Var(X_i)$ 

Random Vectors

# Multivariate Gaussian Distribution

A multivariate Gaussian random variable  $X \sim \mathcal{N}(\mu, \Sigma)$  can be defined as

$$f_{X_1,...,X_n}(x_1,...,x_n) = \frac{1}{\sqrt{(2\pi)^n} |\Sigma|^{1/2}} \exp(-\frac{1}{2}(x-\mu)^T \Sigma^{-1}(x-\mu))$$

If variables  $X_1, \ldots, X_n$  are uncorrelated, the covariance matrix  $\Sigma$  will become a diagonal matrix with variances of individual variables in its main diagonal. In this case,

$$f_{X_1,...,X_n}(x_1,...,x_n) = \prod_{i=1}^n \frac{1}{\sqrt{2\pi\sigma_i}} \exp(-\frac{(x_i-\mu_i)^2}{2\sigma_i^2})$$